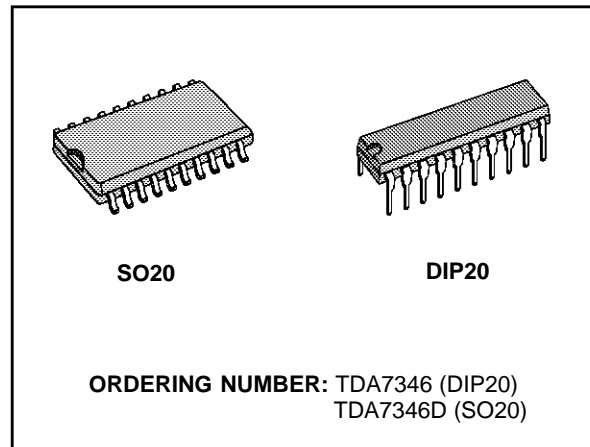


DIGITAL CONTROLLED SURROUND SOUND MATRIX

PRODUCT PREVIEW

- 1 STEREO INPUT
- THREE INDEPENDENT SURROUND MODES ARE AVAILABLE MOVIE, MUSIC AND SIMULATED
 - MUSIC: 4 SELECTABLE RESPONSES
 - MOVIE AND SIMULATED: 256 SELECTABLE RESPONSES
- TWO INDEPENDENT INPUT ATTENUATORS IN 0.31dB FOR BALANCE FACILITY
- ALL FUNCTIONS PROGRAMMABLE VIA SERIAL BUS

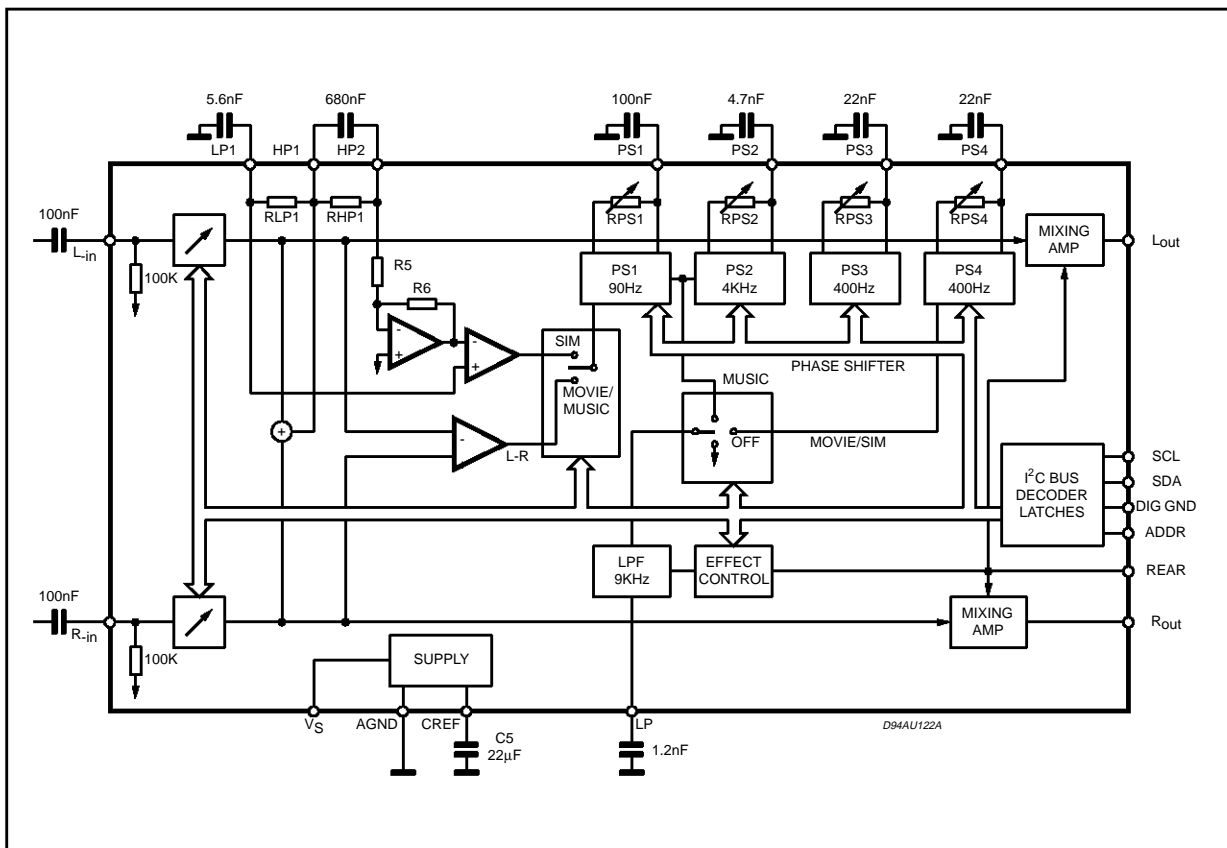


DESCRIPTION

The TDA7346 reproduces surround sound by using phase shifters and a signal matrix. Control of all the functions is accomplished by serial bus. The AC signal setting is obtained by resistor network

and switches combined with operational amplifiers.

BLOCK DIAGRAM

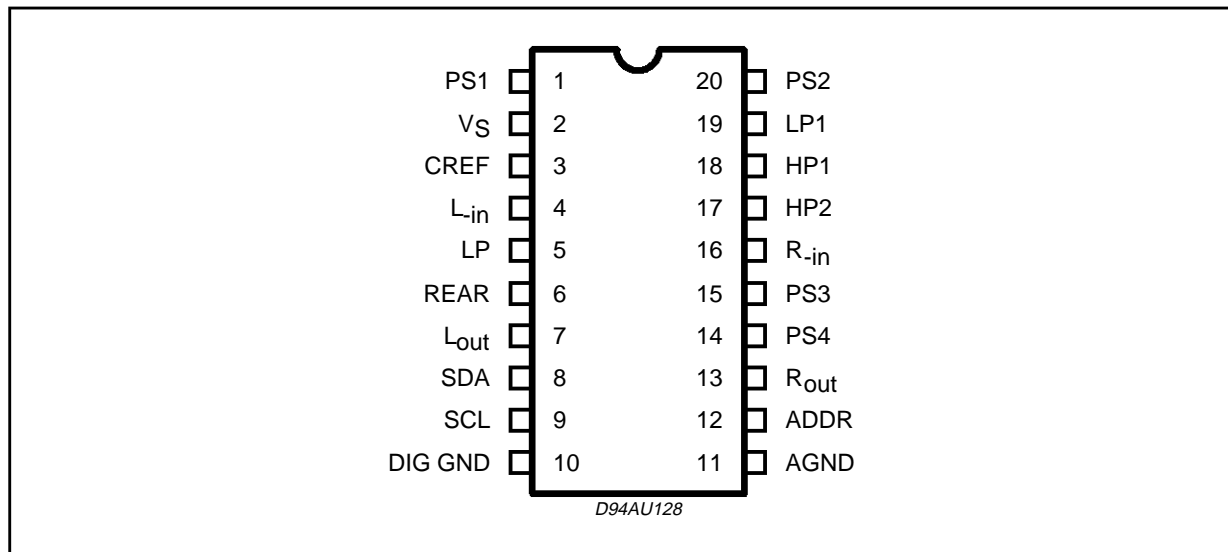


TDA7346

ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	Value	Unit
V _S	Operating Supply Voltage	10.5	V
T _{amb}	Operating Ambient Temperature	-40 to 85	°C
T _{stg}	Storage Temperature Range	-55 to +150	°C

PIN CONNECTION



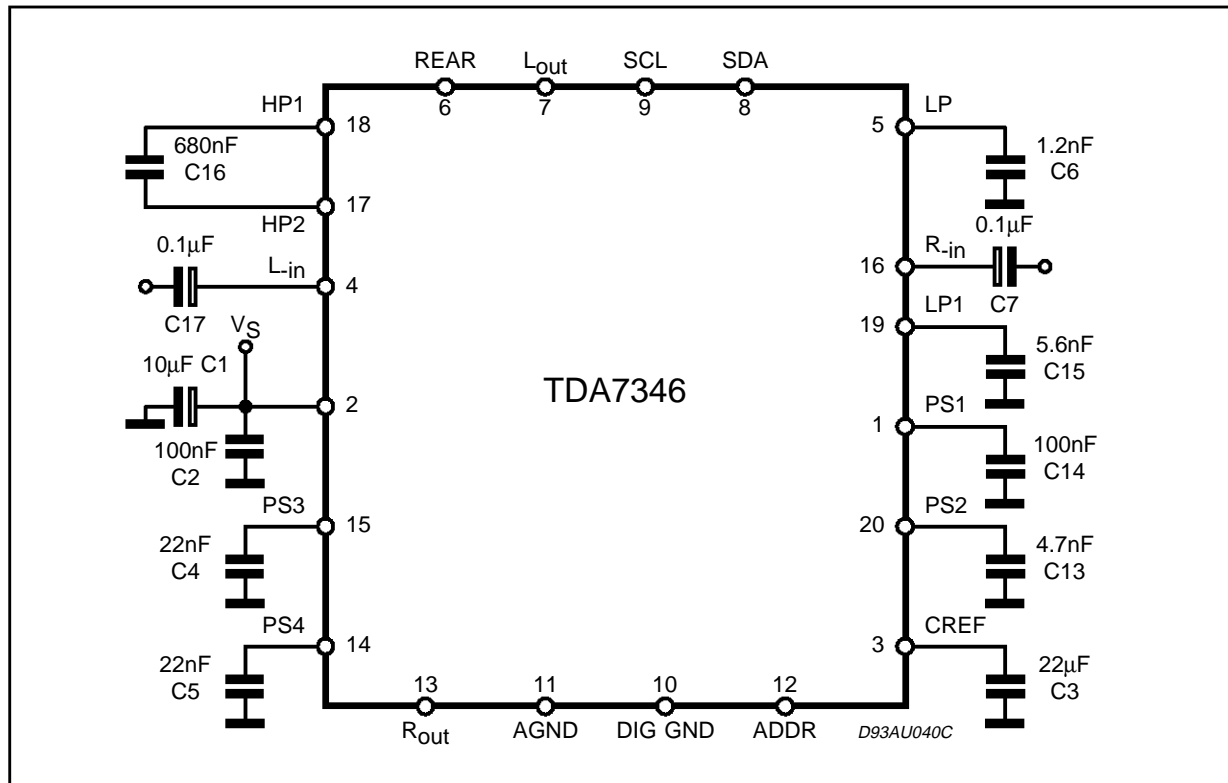
THERMAL DATA

Symbol	Description	Value	Unit
R _{th j-pins}	Thermal Resistance Junction-pins	Max. 85	°C/W

QUICK REFERENCE DATA

Symbol	Parameter	Min.	Typ.	Max.	Unit
V _S	Supply Voltage	7	9	10.2	V
V _{CL}	Max. input signal handling	2			V _{rms}
THD	Total Harmonic Distortion V = 1V _{rms} f = 1KHz		0.02	0.1	%
S/N	Signal to Noise Ratio V _{out} = 1V _{rms} (mode = OFF)		106		dB
S _c	Channel Separation f = 1KHz		70		dB

TEST CIRCUIT



ELECTRICAL CHARACTERISTICS (refer to the test circuit $T_{amb} = 25^{\circ}\text{C}$, $V_S = 9\text{V}$, $R_L = 10\text{k}\Omega$, $R_G = 600\Omega$, all controls flat ($G = 0$), Effect Ctrl = -6dB, MODE = OFF; $f = 1\text{KHz}$ unless otherwise specified)

Symbol	Parameter	Test Condition	Min.	Typ.	Max.	Unit
--------	-----------	----------------	------	------	------	------

SUPPLY

V_S	Supply Voltage		7	9	10.2	V
I_S	Supply Current			10		mA
SVR	Ripple Rejection	LCH / RCH out, Mode = OFF	60	80		dB

INPUT STAGE

R_{II}	Input Resistance			100		$\text{k}\Omega$
V_{CL}	Clipping Level	THD = 0.3%; Lin or Rin	2	2.5		V _{rms}
		THD = 0.3%; Rin + Lin (2)		3.0		V _{rms}
C_{RANGE}	Control Range			20		dB
$A_{V_{MIN}}$	Min. Attenuation		-1	0	1	dB
$A_{V_{MAX}}$	Max. Attenuation			20		dB
A_{STEP}	Step Resolution			0.31		dB
V_{DC}	DC Steps	adjacent att. step		0		mV

EFFECT CONTROL

C_{RANGE}	Control Range		-21		-6	dB
S_{STEP}	Step Resolution			1		dB

ELECTRICAL CHARACTERISTICS (continued)
SURROUND SOUND MATRIX

Symbol	Parameter	Test Condition	Min.	Typ.	Max.	Unit
G _{OFF}	In-phase Gain (OFF)	Mode OFF, Input signal of 1kHz, 1.4 V _{p-p} , R _{in} → R _{out} L _{in} → L _{out}	-1.5	0	1.5	dB
D _{G_{OFF}}	LR In-phase Gain Difference (OFF)	Mode OFF, Input signal of 1kHz, 1.4 V _{p-p} (R _{in} → R _{out}), (L _{in} → L _{out})	-1.5	0	1.5	dB
G _{MOV1}	In-phase Gain (Movie 1) RPS1, RPS2, RPS3, RPS4 = POR Preset	Movie mode, Effect Ctrl = -6dB Input signal of 1kHz, 1.4 V _{p-p} R _{in} → R _{out} , L _{in} → L _{out}		7		dB
G _{MOV2}	In-phase Gain (Movie 2) RPS1, RPS2, RPS3, RPS4 = POR Preset	Movie mode, Effect Ctrl = -6dB Input signal of 1kHz, 1.4 V _{p-p} R _{in} → R _{out} , L _{in} → L _{out}		8		dB
D _{G_{MOV}}	LR In-phase Gain Difference (Movie)	Movie mode, Effect Ctrl = -6dB Input signal of 1kHz, 1.4 V _{p-p} (R _{in} → R _{out}) - (L _{in} → L _{out})		0		dB
G _{MUS1}	In-phase Gain (Music 1) RPS1 = POR PRESET	Music mode, Effect Ctrl = -6dB Input signal of 1kHz, 1.4 V _{p-p} (R _{in} → R _{out}) - (L _{in} → L _{out})		6		dB
G _{MUS2}	In-phase Gain (Music 2) RPS1 = POR PRESET	Music mode, Effect Ctrl = -6dB Input signal of 1kHz, 1.4 V _{p-p} R _{in} → R _{out} , L _{in} → L _{out}		7.5		dB
D _{G_{MUS}}	LR In-phase Gain Difference (Music)	Music mode, Effect Ctrl = -6dB Input signal of 1kHz, 1.4 V _{p-p} (R _{in} → R _{out}) - (L _{in} → L _{out})		0		dB
L _{MON1}	Simulated L Output 1 RPS1, RPS2, RPS3, RPS4 = POR Preset	Simulated Mode, Effect Ctrl = -6dB Input signal of 250Hz, 1.4 V _{p-p} , R _{in} and L _{in} → L _{out}		4.5		dB
L _{MON2}	Simulated L Output 2 RPS1, RPS2, RPS3, RPS4 = POR Preset	Simulated Mode, Effect Ctrl = -6dB Input signal of 1kHz, 1.4 V _{p-p} , R _{in} and L _{in} → L _{out}		- 4.0		dB
L _{MON3}	Simulated L Output 3 RPS1, RPS2, RPS3, RPS4 = POR Preset	Simulated Mode, Effect Ctrl = -6dB Input signal of 3.6kHz, 1.4 V _{p-p} , R _{in} and L _{in} → L _{out}		7.0		dB
R _{MON1}	Simulated R Output 1 RPS1, RPS2, RPS3, RPS4 = POR Preset	Simulated Mode, Effect Ctrl = -6dB Input signal of 250Hz, 1.4 V _{p-p} , R _{in} and L _{in} → R _{out}		- 4.5		dB
R _{MON2}	Simulated R Output 2 RPS1, RPS2, RPS3, RPS4 = POR Preset	Simulated Mode, Effect Ctrl = -6dB Input signal of 1kHz, 1.4 V _{p-p} , R _{in} and L _{in} → R _{out}		3.8		dB
R _{MON3}	Simulated R Output 3 RPS1, RPS2, RPS3, RPS4 = POR Preset	Simulated Mode, Effect Ctrl = -6dB Input signal of 3.6kHz, 1.4 V _{p-p} , R _{in} and L _{in} → R _{out}		- 20		dB
R _{LP1}	Low Pass Filter Resistance			10		KΩ
R _{PS1}	Phase Shifter 1 Resistance	at POR		17.95		kΩ
R _{PS2}	Phase Shifter 2 Resistance	at POR		8.465		KΩ
R _{PS3}	Phase Shifter 3 Resistance	at POR		18.050		KΩ
R _{PS4}	Phase Shifter 4 Resistance	at POR		18.050		KΩ
R _{HPI}	High Pass Filter Resistance			60		KΩ
R _{LPF}	LP Pin Impedance			10		KΩ

ELECTRICAL CHARACTERISTICS (continued)

Symbol	Parameter	Test Condition	Min.	Typ.	Max.	Unit
--------	-----------	----------------	------	------	------	------

AUDIO OUTPUTS

V _{OCL}	Clipping Level	d = 0.3%	2	2.5		V _{rms}
R _{OUT}	Output resistance		100	200	300	Ω
V _{OUT}	DC Voltage Level		3.5	3.8	4.1	V

GENERAL

N _{O(OFF)}	Output Noise (OFF)	B _W = 20Hz to 20KHz R _{out} and L _{out} measurement		8		μV _{rms}
N _{O(MOV)}	Output Noise (Movie)	Mode =Movie , B _W = 20Hz to 20KHz R _{out} and L _{out} measurement		30		μV _{rms}
N _{O(MUS)}	Output Noise (Music)	Mode = Music , B _W = 20Hz to 20KHz, R _{out} and L _{out} measurement		30		μV _{rms}
N _{O(MON)}	Output Noise (Simulated)	Mode = Simulated, B _W = 20Hz to 20KHz R _{out} and L _{out} measurement		30		μV _{rms}
d	Distorsion	Av = 0 ; V _{in} = 1V _{rms}		0.02	0.1	%
S _C	Channel Separation			70		dB

BUS INPUTS

V _{IL}	Input Low Voltage				1	V
V _{IH}	Input High Voltage		3			V
I _{IN}	Input Current		-5		+5	μA
V _O	Output Voltage SDA Acknowledge	I _O = 1.6mA		0.4	0.8	V

Note:

(1) Bass and Treble response: The center frequency and the resonance quality can be chosen by the external circuitry. A standard first order bass response can be realized by a standard feedback network.

(2) The peak voltage of the two input signals must be less than $\frac{V_s}{2}$:

$$(I_{in} + R_{in})_{peak} \cdot A_{vin} < \frac{V_s}{2}$$

I²C BUS INTERFACE

Data transmission from microprocessor to the TDA7346 and viceversa takes place through the 2 wires I²C BUS interface, consisting of the two lines SDA and SCL (pull-up resistors to positive supply voltage must be connected).

Data Validity

As shown in fig. 3, the data on the SDA line must be stable during the high period of the clock. The HIGH and LOW state of the data line can only change when the clock signal on the SCL line is LOW.

Start and Stop Conditions

As shown in fig.4 a start condition is a HIGH to LOW transition of the SDA line while SCL is HIGH. The stop condition is a LOW to HIGH transition of the SDA line while SCL is HIGH.

Byte Format

Every byte transferred on the SDA line must contain 8 bits. Each byte must be followed by an ac-

knowledge bit. The MSB is transferred first.

Acknowledge

The master (μ P) puts a resistive HIGH level on the SDA line during the acknowledge clock pulse (see fig. 5). The peripheral (audioprocessor) that acknowledges has to pull-down (LOW) the SDA line during the acknowledge clock pulse, so that the SDA line is stable LOW during this clock pulse.

The audioprocessor which has been addressed has to generate an acknowledge after the reception of each byte, otherwise the SDA line remains at the HIGH level during the ninth clock pulse time. In this case the master transmitter can generate the STOP information in order to abort the transfer.

Transmission without Acknowledge

Avoiding to detect the acknowledge of the audioprocessor, the μ P can use a simpler transmission: simply it waits one clock without checking the slave acknowledging, and sends the new data.

This approach of course is less protected from misworking and decreases the noise immunity.

Figure 3: Data Validity on the I²C BUS

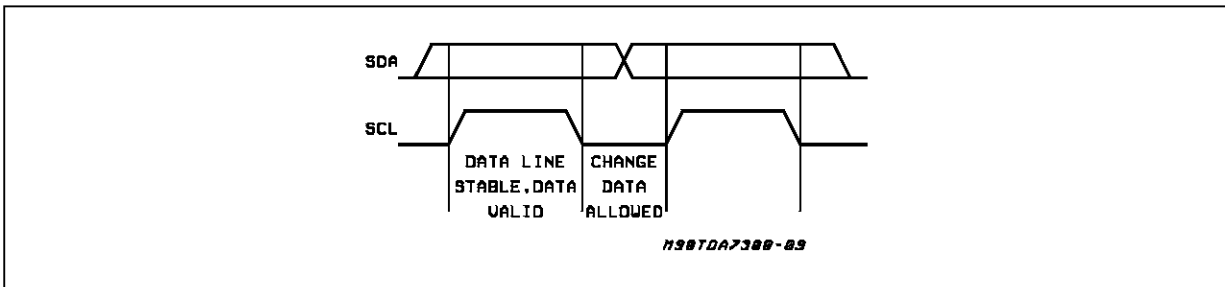


Figure 4: Timing Diagram of I²C BUS

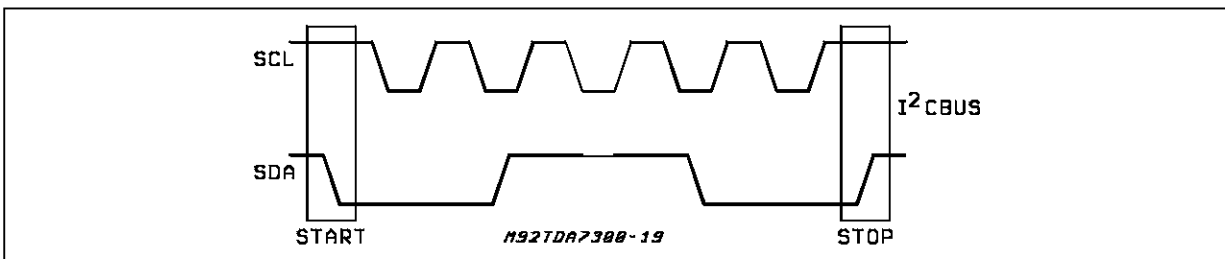
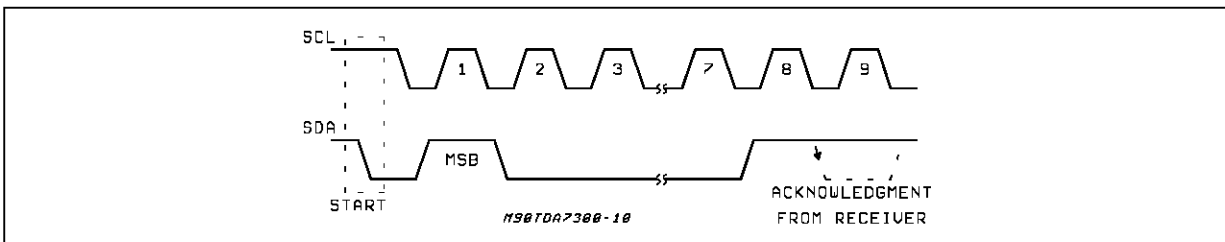


Figure 5: Acknowledge on the I²C BUS



SOFTWARE SPECIFICATION

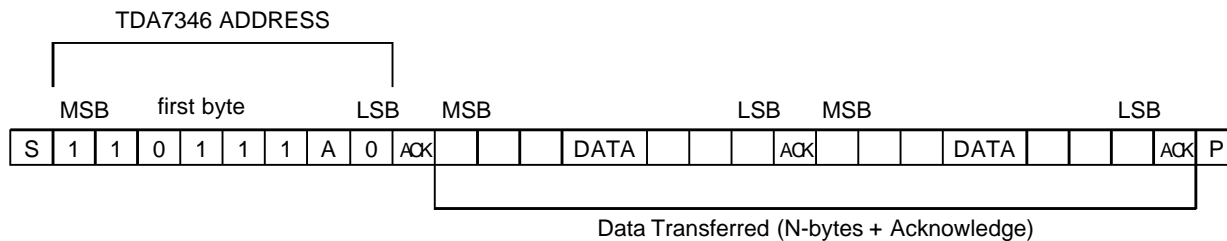
Interface Protocol

The interface protocol comprises:

- A start condition (s)
- A chip address byte, containing the TDA7346

address (the 8th bit of the byte must be 0). The TDA7346 must always acknowledge at the end of each transmitted byte.

- A sequence of data (N bytes + acknowledge).
- A stop condition (P)



ACK = Acknowledge
 S = Start
 P = Stop

MAX CLOCK SPEED 100kbits/s

SOFTWARE SPECIFICATION

Chip address

1	1	0	1	1	1	A	0
MSB							LSB

A	CHIP ADDRESS
0	DC (HEX)
1	DE (HEX)

A = Logic level on pin ADDR

A = 1 if ADDR pin = open

A = 0 if ADDR pin = connected to ground

Software Specification

MSB							LSB	SUBADDRESS
0	0	A5	A4	A3	A2	A1	A0	INPUT ATTENUATION R
0	1	A5	A4	A3	A2	A1	A0	INPUT ATTENUATION L
1	M1	M0						SURROUND MODES
1	0	0						SIMULATED MODE
1	0	1						MUSIC MODE
1	1	0						MOVIE MODE
1	1	1						OFF MODE
1	M1	M0	1	B3	B2	B1	B0	EFFECT CONTROL
1	M1	M0	0	0	0	C1	C0	PHASE SHIFTER 4 CONTROL
1	M1	M0	0	0	1	C1	C0	PHASE SHIFTER 3 CONTROL
1	M1	M0	0	1	0	D1	D0	PHASE SHIFTER 2 CONTROL
1	M1	M0	0	1	1	E1	E0	PHASE SHIFTER 1 CONTROL

TDA7346

INPUT ATTENUATION								
MSB							LSB	0.3125 dB STEPS
	I	A5	A4	A3	A2	A1	A0	
0					0	0	0	0
0					0	0	1	-0.3125
0					0	1	0	-0.625
0					0	1	1	-0.9375
0					1	0	0	-1.25
0					1	0	1	-1.5625
0					1	1	0	-1.875
0					1	1	1	-2.1875
								2.5 dB STEPS
0		0	0	0				0
0		0	0	1				-2.5
0		0	1	0				-5
0		0	1	1				-7.5
0		1	0	0				-10
0		1	0	1				-12.5
0		1	1	0				-15
0		1	1	1				-17.5

I = 0 Attenuation Input R

I = 1 Attenuation Input L

Example: to program an R input attenuation equal to -11.25 you have to send 00100100

EFFECT CONTROL (-6 / -21dB)								
MSB							LSB	1dB STEPS
				B3	B2	B1	B0	
1	M1	M0	1	0	0	0	0	-6
1	M1	M0	1	0	0	0	1	-7
1	M1	M0	1	0	0	1	0	-8
1	M1	M0	1	0	0	1	1	-9
1	M1	M0	1	0	1	0	0	-10
1	M1	M0	1	0	1	0	1	-11
1	M1	M0	1	0	1	1	0	-12
1	M1	M0	1	0	1	1	1	-13
1	M1	M0	1	1	0	0	0	-14
1	M1	M0	1	1	0	0	1	-15
1	M1	M0	1	1	0	1	0	-16
1	M1	M0	1	1	0	1	1	-17
1	M1	M0	1	1	1	0	0	-18
1	M1	M0	1	1	1	0	1	-19
1	M1	M0	1	1	1	1	0	-20
1	M1	M0	1	1	1	1	1	-21

PHASE SHIFTER 3, 4								
MSB							LSB	RESISTOR VALUE (K Ω)
						C1	C0	
1	M1	M0	0	0	F	0	0	12.060
1	M1	M0	0	0	F	0	1	14.450
1	M1	M0	0	0	F	1	0	18.050
1	M1	M0	0	0	F	1	1	39.100

F = 0 Phase Shifter 4

F = 1 Phase Shifter 3

PHASE SHIFTER 2								
MSB							LSB	RESISTOR VALUE (K Ω)
						D1	D0	
1	M1	M0	0	1	0	0	0	5.640
1	M1	M0	0	1	0	0	1	6.770
1	M1	M0	0	1	0	1	0	8.465
1	M1	M0	0	1	0	1	1	18.300

PHASE SHIFTER 1								
MSB							LSB	RESISTOR VALUE (K Ω)
						E1	E0	
1	M1	M0	0	1	1	0	0	11.745
1	M1	M0	0	1	1	0	1	14.150
1	M1	M0	0	1	1	1	0	17.950
1	M1	M0	0	1	1	1	1	37.625

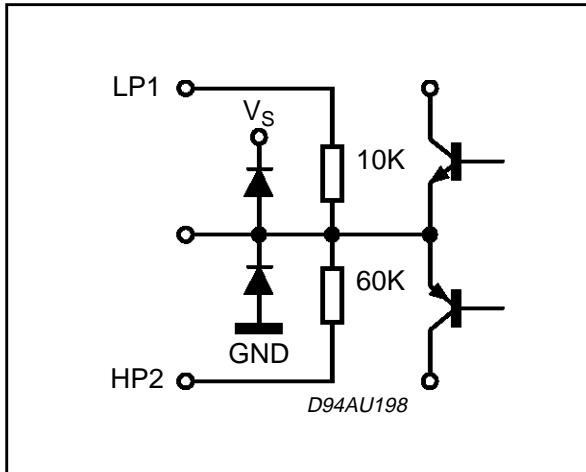
Example: to program MOVIE MODE with EFFECT control = -7dB with PHASE SHIFTER resistor = 11.745K Ω , PHASE SHIFTER 2 resistor = 6.77K Ω , PHASE SHIFTER 3 resistor = 12.06K Ω , PHASE SHIFTER 4 resistor = 18.05K Ω , you have to send in sequence 5 bytes:

```
11010001
11001100
11001001
11000100
11000010
```

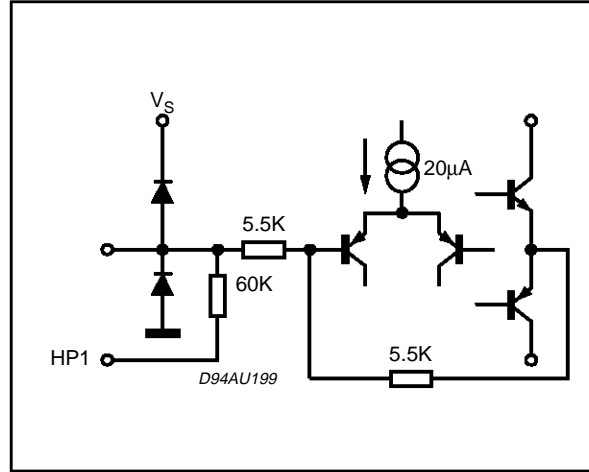
POWER ON RESET	
INPUT ATTENUATION	-19.375dB
EFFECT CONTROL	-20dB
SURROUND MODE	OFF MODE
PHASE SHIFTER 1 RESISTOR VALUE	17.950 K Ω
PHASE SHIFTER 2 RESISTOR VALUE	8.465 K Ω
PHASE SHIFTER 3, 4 RESISTOR VALUE	18.050 K Ω

TDA7346

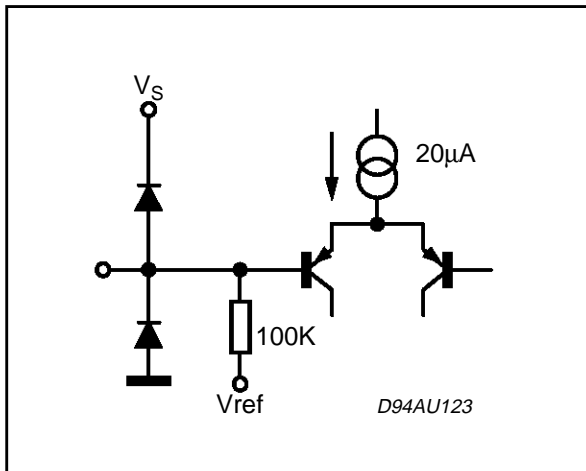
PIN: HP1



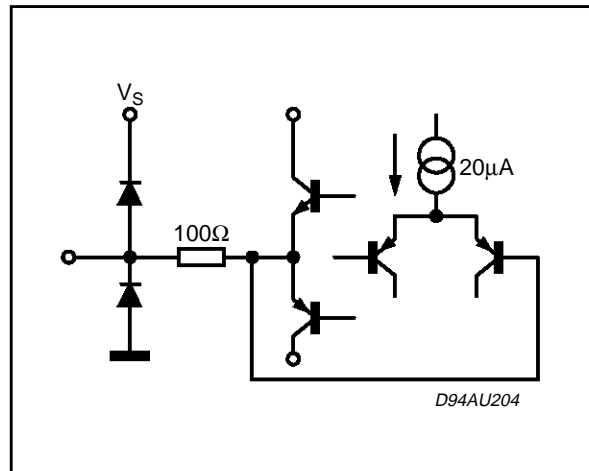
PIN: HP2



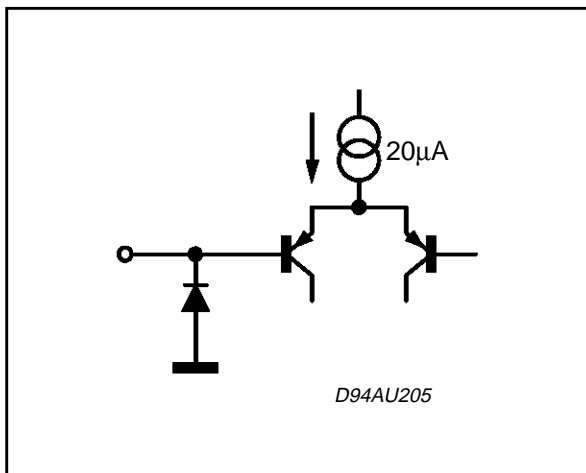
PIN: Lin, Rin



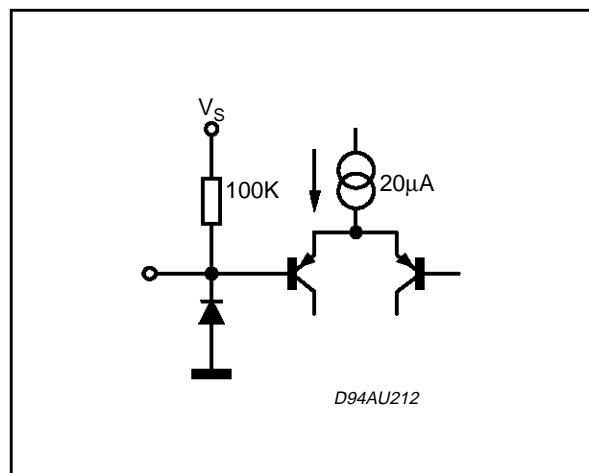
PIN: Lout, Rout, REAR



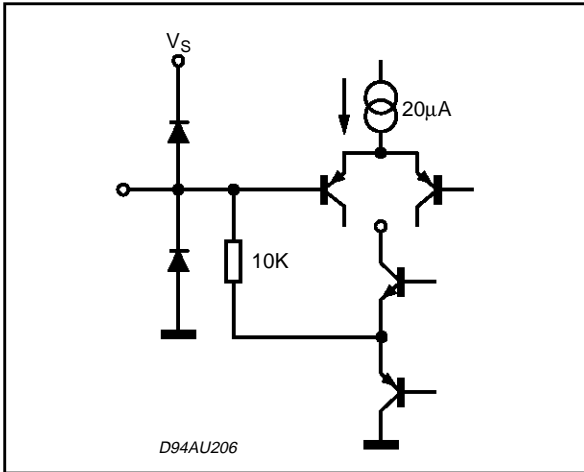
PIN: SCL, SDA



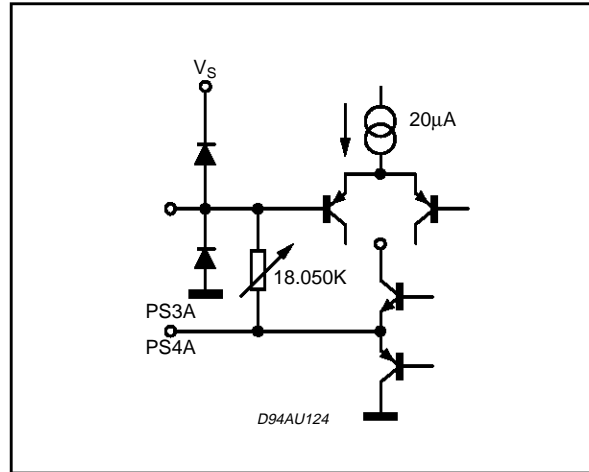
PIN: ADDR



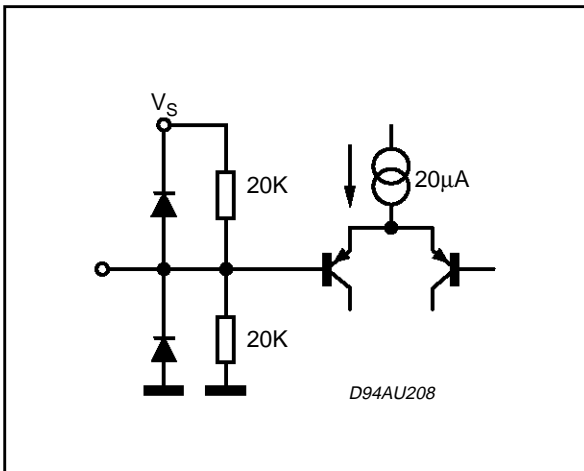
PIN: LP



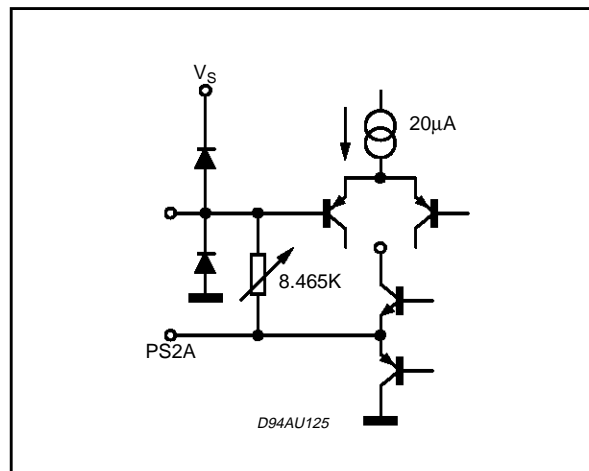
PIN: PS3, PS2



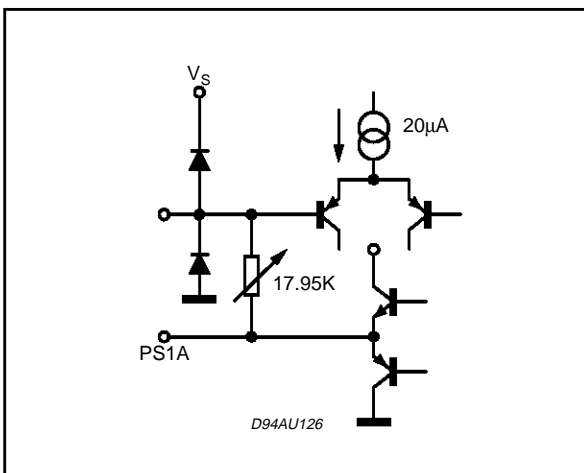
PIN: C_{REF}



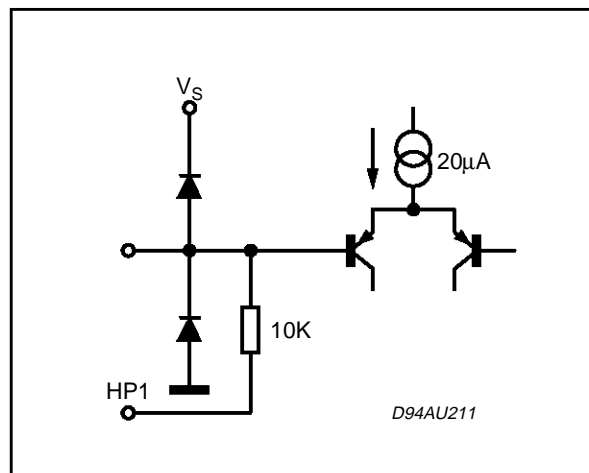
PIN: PS2



PIN: PS1

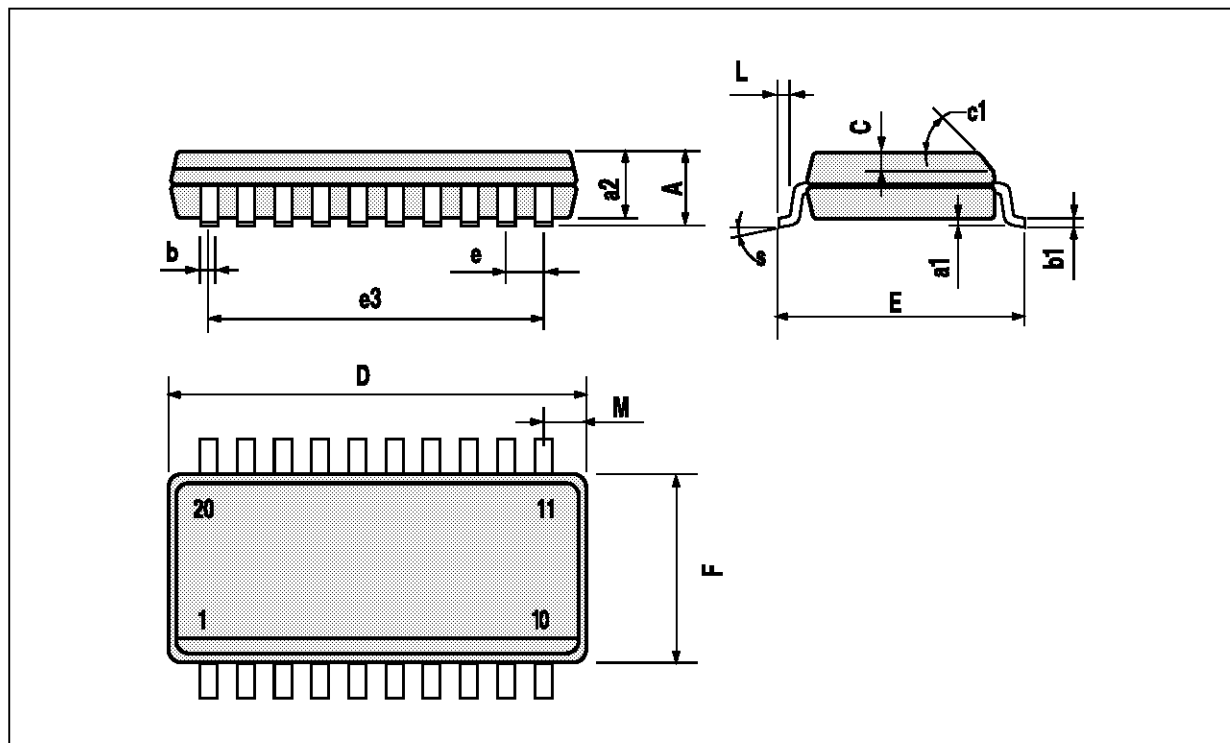


PIN: LP1



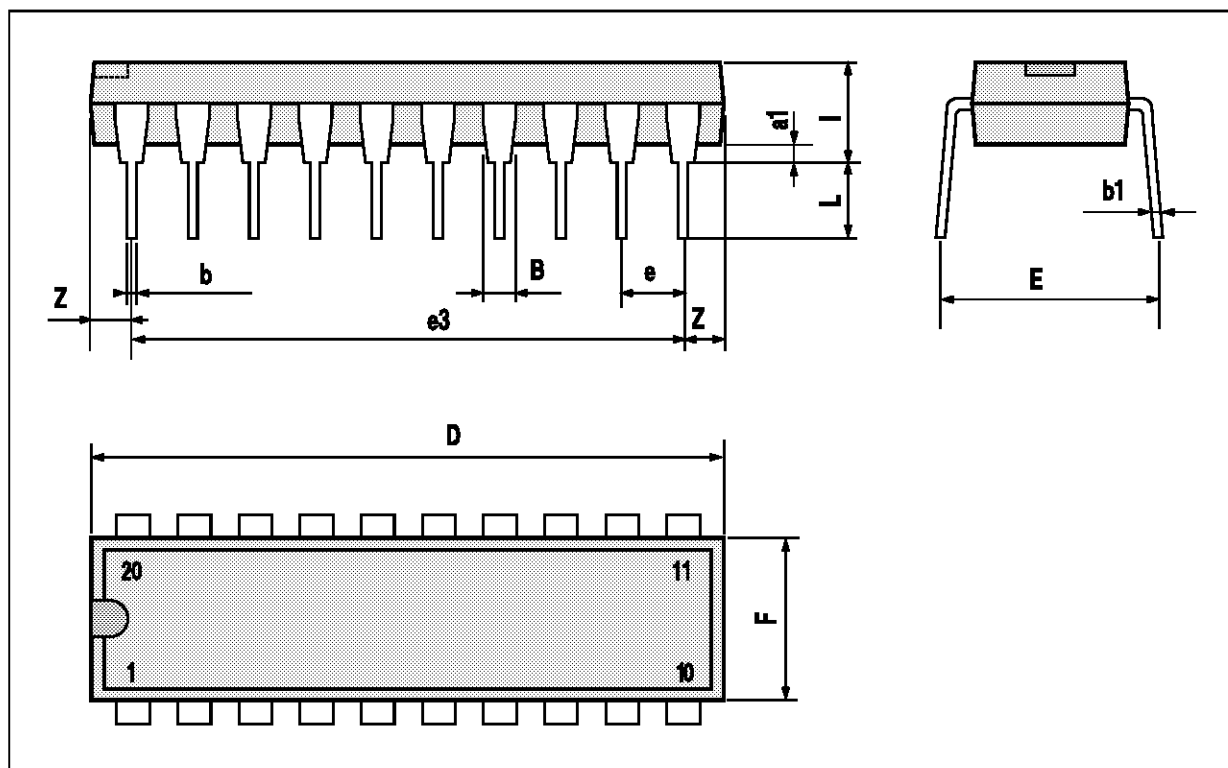
SO20 PACKAGE MECHANICAL DATA

DIM.	mm			inch		
	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.
A			2.65			0.104
a1	0.1		0.3	0.004		0.012
a2			2.45			0.096
b	0.35		0.49	0.014		0.019
b1	0.23		0.32	0.009		0.013
C		0.5			0.020	
c1	45° (typ.)					
D	12.6		13.0	0.496		0.512
E	10		10.65	0.394		0.419
e		1.27			0.050	
e3		11.43			0.450	
F	7.4		7.6	0.291		0.299
L	0.5		1.27	0.020		0.050
M			0.75			0.030
S	8° (max.)					



DIP20 PACKAGE MECHANICAL DATA

DIM.	mm			inch		
	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.
a1	0.254			0.010		
B	1.39		1.65	0.055		0.065
b		0.45			0.018	
b1		0.25			0.010	
D			25.4			1.000
E		8.5			0.335	
e		2.54			0.100	
e3		22.86			0.900	
F			7.1			0.280
l			3.93			0.155
L		3.3			0.130	
Z			1.34			0.053



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